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# Introduction to Stan

Cameron Bracken  
*University of Colorado Boulder*



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# What is Stan?

*"A probabilistic programming language implementing full Bayesian statistical inference with MCMC sampling (NUTS, HMC) and penalized maximum likelihood estimation with Optimization (L-BFGS)"*



"Stanislaw Ulam, namesake of Stan and co-inventor Monte Carlo methods shown here holding the Fermiac, Enrico Fermi's physical Monte Carlo simulator for neutron diffusion."  
(image from the Stan manual)

# Bayesian Statistics

*By Bayesian data analysis, we mean practical methods for making inferences from data using probability models for quantities we observe and about which we wish to learn.*

*The essential characteristic of Bayesian methods is their explicit use of probability for quantifying uncertainty in inferences based on statistical analysis.*

[Gelman et al., Bayesian Data Analysis, 3rd edition, 2013]

# Background on Bayesian Statistics

From Bayes' rule, supposing the data is fixed (observed):

$$\begin{aligned} p(\theta|y) &= \frac{p(y,\theta)}{p(y)} = \frac{p(y|\theta)p(\theta)}{p(y)} \\ &= \frac{p(y|\theta)p(\theta)}{\int p(y,\theta)d\theta} \\ &= \frac{p(y|\theta)p(\theta)}{\int p(y|\theta)p(\theta)d\theta} \\ p(\theta|y) &\propto p(y|\theta)p(\theta) = p(y,\theta) \end{aligned}$$

- ▶ Everyone: Model data as random
- ▶ Bayesians: Model parameters as random

# Background on Bayesian Statistics

From Bayes' rule:

$$\underbrace{p(\theta|y, x)}_{\text{Posterior}} \propto \underbrace{p(y|\theta, x)}_{\text{Likelihood}} \underbrace{p(\theta, x)}_{\text{Prior}}$$

$\theta$  Parameters

$y$  Dependent data (response)

$x$  Independent data (covariates/predictors/constants)

**Posterior:** The answer, probability distributions of parameters

**Likelihood:** A computable function of the parameters, model specific

**Prior:** "Initial guess", incorporates existing knowledge of the system

The key to building Bayesian models is specifying the likelihood function, same as frequentist.

# Monte Carlo Markov Chain (MCMC) in a nutshell

- ▶ We want to generate random draws from a target distribution (the posterior). We then identify a way to construct a 'nice' markov chain such that its equilibrium probability distribution is our target distribution.
- ▶ If we can construct such a chain then we arbitrarily start from some point and iterate the markov chain many times (like how we forecasted the weather n times). Eventually, the draws we generate would appear as if they are coming from our target distribution.
- ▶ There are several ways to construct 'nice' markov chains (e.g., gibbs sampler, Metropolis-Hastings algorithm).

(explanation from Cross Validated)

- MCMC is really a way to solve integrals that are impossible to solve analytically.

# What does stan do?

- ▶ Samples from the posterior distribution (if your model is specified correctly)
- ▶ "Fits" bayesian models
- ▶ Empowers you to write your own Bayesian models, it's much easier than you think!



## No U-Turn Sampler

Automatic Step Size and  
Number Adaptation

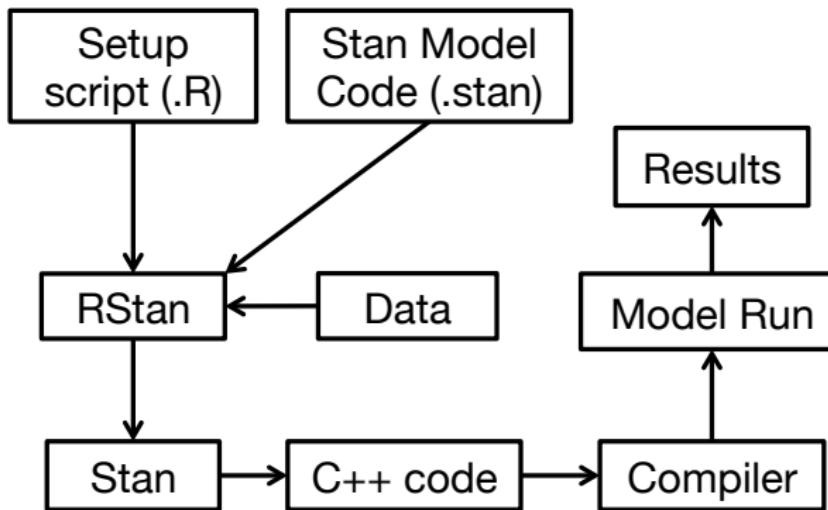
# Why Stan?

There are tons of other “black-box” MCMC samplers out there  
(BUGS, JAGS, Church, PyMC, many many more,  
<http://probabilistic-programming.org/wiki/Home>)

- ▶ Stan is open source
- ▶ Built to be fast (about 10 times faster than BUGS according Gelman)
- ▶ “Stan can handle problems that choke BUGS and JAGS” – Andrew Gelman

# Using Stan

Stan is a library with a number of interfaces, we will use the R interface called RStan.



# Example 1 – Fit Normal Distribution – Model code

Download from: [http://bechtel.colorado.edu/~bracken/stan/example\\_models.zip](http://bechtel.colorado.edu/~bracken/stan/example_models.zip)

Example files in 1-normal: normal.stan/normal.R

```
data {  
    int<lower=0> N; // error checking for N  
    vector[N] y;  
}  
  
parameters {  
    real<lower=0> sigma;  
    real mu;  
}  
  
model {  
    y ~ normal(mu, sigma); //vectorized  
}
```

# Example 1 – Fit Normal Distribution – RStan code

```
library(RStan)
model_file = 'normal.stan'
iterations = 500
N = 1000
mu = 100
sigma = 10
y = rnorm(N, mu,sigma) # simulate data

stan_data = list(N=N, y=y) # data passed to stan
# set up the model
stan_model = stan(model_file, data = stan_data, chains = 0)
stanfit = stan(fit = stan_model, data = stan_data,
iter=iterations) # run the model
print(stanfit,digits=2)
```

# Diagnostics - Text output

Inference for Stan model: normal.

4 chains, each with iter=500; warmup=250; thin=1;  
post-warmup draws per chain=250, total post-warmup draws=1000.

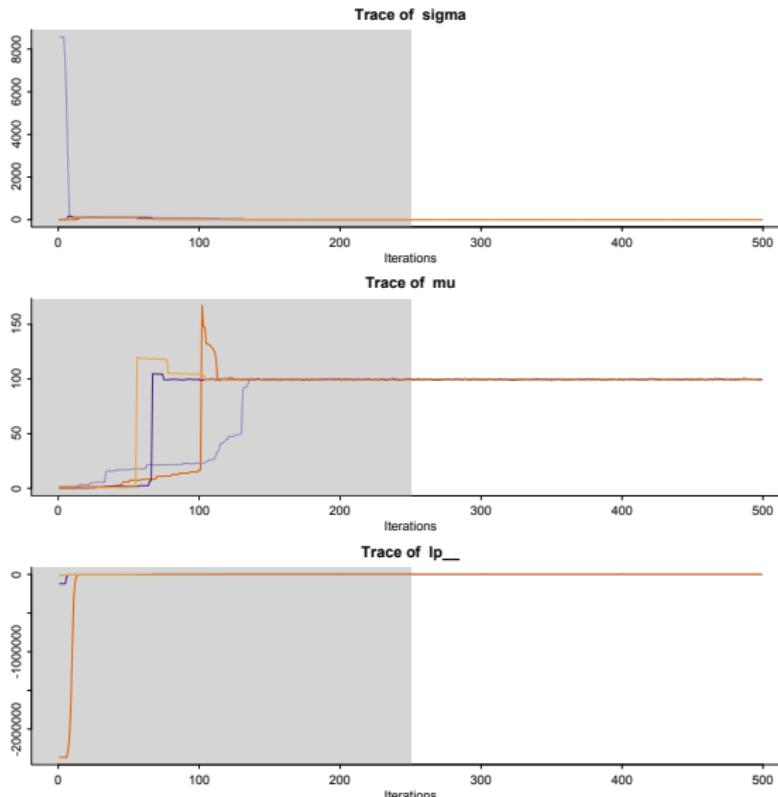
	mean	se_mean	sd	2.5%	25%	50%	75%	97.5%	n_eff	Rhat
sigma	9.84	0.01	0.19	9.47	9.72	9.84	9.98	10.23	366	1.01
mu	99.68	0.01	0.31	99.08	99.48	99.69	99.88	100.30	617	1.00
lp__	-2785.83	0.04	0.87	-2788.07	-2786.19	-2785.58	-2785.19	-2784.97	395	1.00

Samples were drawn using NUTS(diag\_e) at Thu Feb 19 21:04:56 2015.

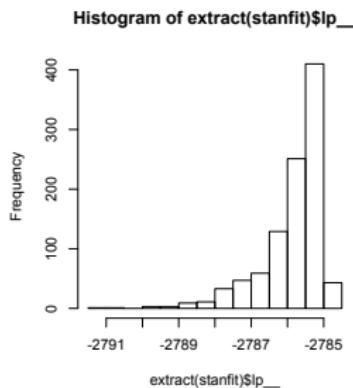
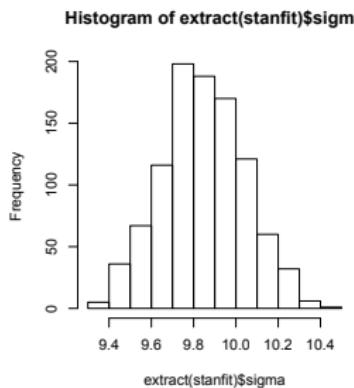
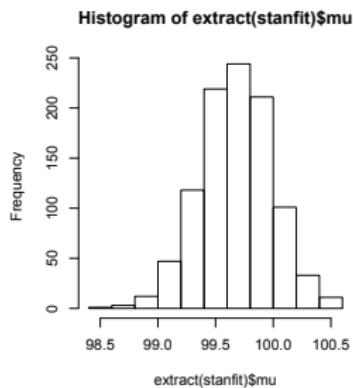
For each parameter, n\_eff is a crude measure of effective sample size,  
and Rhat is the potential scale reduction factor on split chains (at  
convergence, Rhat=1).

- ▶ thin, warmup
- ▶  $n_{eff}$
- ▶  $\hat{R}$
- ▶ lp\_\_

# Diagnostics - Traceplots



# Diagnostics - Posterior plots



# Diagnostics - shinyStan

Old package (don't use it):

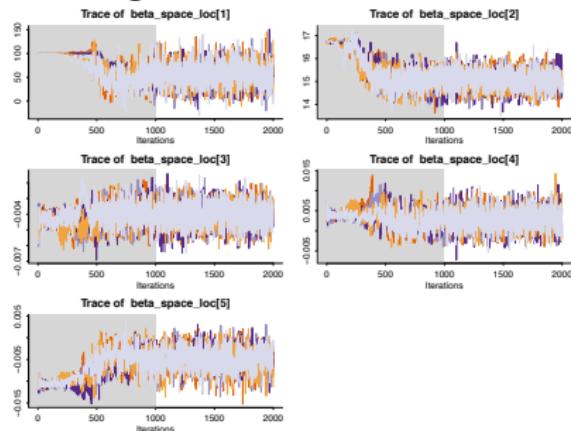
<https://github.com/jgabry/SHINYstan>

Changing to: <https://github.com/shinyStan/shinyStan>

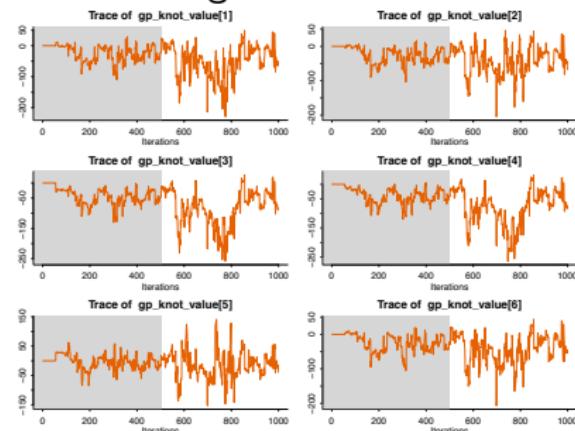
```
library("shinyStan")
launch_shinystan(stanfit)
```

# Convergence - Traceplots

Converged:

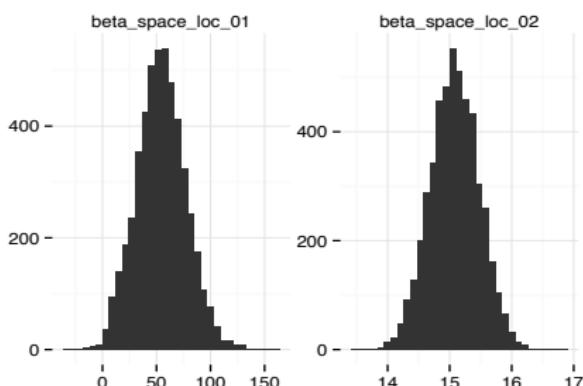


Not Converged:

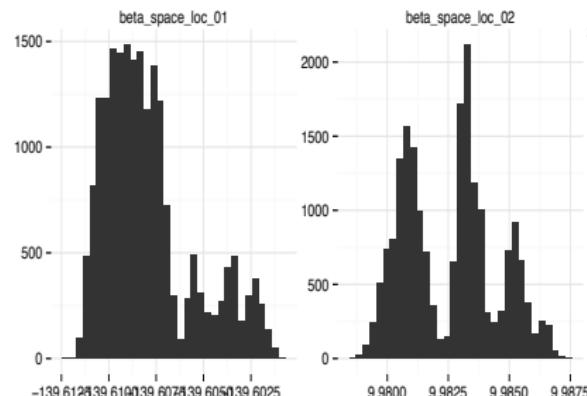


# Convergence - Posterior plots

Converged:



Not Converged:



## Example 2 – Fit normal distribution (fancier)

$$y_n \sim \text{Normal}(\mu, \sigma)$$

The likelihood of observing a normally distributed data value is the normal density of that point given the parameter values.

Example files in 2-normal: `normal2.stan/normal2.R`

- ▶ priors
- ▶ initial values

# Example 3 – fit GEV distribution

Generalized extreme value distribution

$$y \sim GEV(\mu, \sigma, \xi)$$

$\mu$ : location,  $\sigma$ : scale,  $\xi$ : shape

Example files in 3-gev: `gev.stan/ gev.R`

- ▶ Random seed
- ▶ constraints
- ▶ variable constraints
- ▶ Initial values

## Example 4 - multiple linear regression

$$y_n = \alpha + \beta x_n + \varepsilon_n$$

where  $\varepsilon_n \sim \text{Normal}(0, \sigma)$ , which can be written:

$$y_n - (\alpha + \beta x_n) \sim \text{Normal}(0, \sigma)$$

$$y_n \sim \text{Normal}(\alpha + \beta x_n, \sigma)$$

The likelihood of observing a given  $y_n$  is just the normal density with mean  $\alpha + \beta x_n$  and standard deviation  $\sigma$ .

Example files in 4-multiple-linear-regression:  
`mlr.stan/mlr.R`

## Example 5 - Binomial regression (glm)

$$y_n = \alpha + \beta g^{-1}(x_n) + \varepsilon_n$$

$$y_n \sim \text{Normal}(g^{-1}(x_n), 1)$$

Example files in 5-binomial-logit:

`binomial-logit.stan`/`binomial-logit.R`

- ▶ Hierarchical

# Stan tips and tricks

## #1 tip: Read the Manual! It is excellent

Other things we didn't really talk about:

- ▶ Local variables in the model block, can be used to store intermediate results
- ▶ Matrices vs arrays, Column vector vs row vector
- ▶ Constrained data types
- ▶ Transformed parameters
- ▶ Functions
- ▶ Logical operations/Other types of looping
- ▶ Elementwise operators
- ▶ Built-in functions
- ▶ Print statements
- ▶ Missing data
- ▶ Prediction
- ▶ Discrete variables

# Stan tips and tricks

No need to truncate priors, do that in the parameter bounds

- ▶ **BAD:** setting constraints on parameters but using a prior with other constraints

```
parameters{  
    real alpha; //implies no constraints  
}  
  
model{  
    alpha ~ uniform(0,1);  
}
```

- ▶ **GOOD::**

```
parameters{  
    real <lower=0,upper=1> alpha;  
}  
  
model{  
    #alpha ~ uniform(0,1); // default uniform priors  
}
```

# Stan tips and tricks

- ▶ No need to use conjugate priors
- ▶ Unlike BUGS (or other Gibbs based samplers), avoid super vague priors if you can, i.e. `inv_gamma(0.1,0.1)`
- ▶ When in doubt, use a normal prior, or google it
- ▶ The Stan mailing list is very active

# Speeding up Stan models

- ▶ Avoid repeated operations

```
// 1/alpha is repeated
for(n in 1:N)
    y[n] ~ exponential(1/alpha * x[n]);
```

- ▶ Vectorization is always faster

```
// not vectorized
for(n in 1:N)
    y[n] ~ normal(beta0 + beta1 * x[n], sigma);
//vectorized
y ~ normal(beta0 + beta1 * x, sigma);
```

- ▶ Priors: More informative the better (think better initial conditions), use MLE to get initial estimates
- ▶ Parallelization: can run multiple chains if you have multiple cores, but each chain is still serial
- ▶ More advanced: Access increment\_log\_prob directly